# EE109: Introduction to Embedded Systems Spring 2021 - Final Exam <br> 5/8/21, 2PM - 3:40PM + 20 min to upload 

[Complete all the information in the box below.]
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Name: $\qquad$
Student ID: $\qquad$
Email: @usc.edu

## Lecture section (Circle-One):

| Redekopp | Redekopp | Weber | Qian |
| :---: | :---: | :---: | :---: |
| 9:30 a.m. | 11 a.m. | 12:30 p.m. | 2 p.m. |

Calculators ARE allowed.

| Page | Ques. | Your score | Max score | Recommended <br> Time |
| :--- | :--- | :---: | :---: | :---: |
|  |  |  | 0 | 0 min. |
|  | 1 |  | 8 | 8 min. |
|  | 2 |  | 12 | 10 min. |
|  | 3 |  | 10 | 12 min. |
|  | 4 |  | 12 | 13 min. |
|  | 5 |  | 10 | 15 min. |
|  | 6 |  | 10 | 12 min. |
|  | 7 |  | 8 | 15 min. |
|  | 8 |  | 82 | 15 min. |
|  | Total |  |  |  |
|  |  | Scan/Upload |  | 20 min. |

1. Multiple Choice / Short answer (8 pts.): Answer the questions below.
1.1 An $\qquad$ (ASIC / FPGA) cannot be reconfigured and is fixed once fabricated.
1.2A state machine with 4 flip-flops can implement a state machine with a maximum of $\qquad$ (2 / 4 / $8 / 16$ ) states.
1.3 True / False $\qquad$ Caching breaks logic into multiple stages to overlap their execution.
1.4 Having completed the labs of EE 109, a student should know NOT to:
a.) Use volatile variables in an ISR
b.) Use 'float' and 'double' types if it can be avoided
c.) Use global variables in embedded programs
d.) Use nested if statements to implement a state machine
1.5 To ensure devices correctly interpret the timing of bits sent over an asynchronous RS-232 connection, both devices must use a common
a.) Ground signal
b.) Baud rate
c.) Prescaler
1.6 An edge-triggered D flip-flop can be built from how many level-sensitive D-Latches?
a.) 1
b.) 2
c.) A D flip-flop cannot be built from level-sensitive D-Latches
1.7 A low-resistance ( $R=0$ ) pathway between two points with a voltage difference is referred to as a(n) $\qquad$ (short / open / high-impedance) circuit.
1.8 To make a signal a digital output on the Arduino, set the appropriate bit of the
$\qquad$ (general name of the) register to a $\qquad$ ( $1 / 0$ ).
a.) $\operatorname{DDR~/~} 0$
b.) $\mathrm{PORT} / 0$
c.) $\mathrm{DDR} / 1$
d.) PORT / 1
2. State Machines I (12 pts.): Consider the completed state diagram shown below to answer the questions below.

a.) Complete the state transition table by filling in the next state columns and the output column in the table below.

| Current State |  | Next State |  |  |  | OutputZ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| State | Q1 Q0 | $\begin{gathered} \mathrm{XY}=\mathbf{0} 0 \\ \text { State }^{*} \end{gathered}$ | $\begin{gathered} \hline \mathrm{XY}=\mathbf{0 1} \\ \text { State }^{*} \end{gathered}$ | $\begin{gathered} \mathrm{XY}=\mathbf{1 0} \\ \text { State }^{*} \end{gathered}$ | $\begin{gathered} X Y=11 \\ \text { State }^{*} \end{gathered}$ |  |
| S0 | 00 | S | S | S | S |  |
| S1 | 01 | S | S | S | S | - |
| S2 | 10 | S | S | S | S |  |
| S3 | 11 | S | S | S | S |  |

b.) To implement the reset condition, what should be connected to the following flip flop inputs?
i.) The SET of the Q0 flip-flop should be connected to:
a. RESET
b. ~RESET
c. 0 (GND)
d. 1 (Vdd)
ii.) The CLR of the Q0 flip-flop should be connected to:
a. RESET
b. ~RESET
c. 0 (GND)
d. 1 (Vdd)
iii.) The SET of the Q1 flip-flop should be connected to:
a. RESET
b. ~RESET
c. 0 (GND)
d. 1 (Vdd)
iv.) The CLR of the Q1 flip-flop should be connected to:
a. RESET
b. ~RESET
c. 0 (GND)
d. 1 (Vdd)
3. State Machines II (10 pts). You are given a state machine with 1 flip-flop, Q, and two inputs: $\mathbf{J}$ and $\mathbf{K}$ and two states: S0 and S1 whose desired behavior is shown in the table below. Answer the following questions.

| Current State |  | Next State |  |  |  |  |  |  |  | Output <br> Z |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $J \mathrm{~K}=00$ |  | $\mathrm{J} \mathrm{K}=01$ |  | $\mathrm{J} \mathrm{K}=10$ |  | $\mathrm{J} \mathrm{K}=11$ |  |  |
| State | Q | State* | Q* | State* | Q* | State* | Q* | State* | Q* |  |
| S0 | 0 | S0 | 0 | S0 | 0 | S1 | 1 | S0 | 0 | 1 |
| S1 | 1 | S0 | 0 | S0 | 0 | S1 | 1 | S1 | 1 | 0 |

a.) Use the state table above to complete the corresponding state diagram (fill in/draw all the correct state transitions and be sure to label them correctly based on the table). For each transition you must arrive at a minimal SOP expression (i.e. combine multiple transitions to the same state to form a single, minimal SOP expression for the transition condition). Fill in the Z output values for each state.

b.) Find a minimal, POS equation for $D$ (input to the single flip-flop, $Q$ ) and a minimal equation (SOP or POS) for Z. Show your work below (to get full credit) and put your final answer in the blanks below.

D (minimal POS $)=$ $\qquad$ Z = $\qquad$
4. Datapath Design I (10 pts.): Consider the datapath below with the accompanying table showing the correspondence of the function select bits F [2:0] to the resulting arithmetic operation performed to produce the output R[3:0].. Complete the table for the control signals: H, J, K, C to achieve the desired operations. Finally, find the logic for (only) the signals, H and K. All input and output numbers are 2's complement numbers. Do not worry about overflow.


Complete the table for the values of $\mathbf{H}, \mathbf{J}, \mathbf{K}$, and $\mathbf{C}$. Use $\mathbf{d}$ for don't care where appropriate.

| F2 | F1 | F0 | H | J K | C | Desired Arithmetic Operation <br> (resulting output for R[3:0]) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | x | x |  |  |  | $\mathrm{X}[3: 0]+1$ |
| 1 | 0 | 0 |  |  | $\mathrm{X}[3: 0]-1$ |  |
| 1 | 0 | 1 |  |  | $\mathrm{X}[3: 0]-\mathrm{Y}[3: 0]$ |  |
| 1 | 1 | 0 |  |  | $\mathrm{X}[3: 0]+\mathrm{Y}[3: 0]$ |  |
| 1 | 1 | 1 |  |  | $\mathbf{2 * X}^{\star}[3: 0]$ |  |

What is the minimal SOP logic for H : $\qquad$

What is the minimal SOP logic for K : $\qquad$
5. Adder Design (10 pts.): You are given a 3-bit unsigned number, W[2:0], and three single bit unsigned inputs: $\mathrm{X}, \mathrm{Y}$, and Z . Design a circuit that generates a 2's complement system output F = W - X - Y - Z.
a. Complete the statement to make it true:

The output values for F can range from $\qquad$ decimal to $\qquad$ decimal.
b. Complete the statement to make it true:

To represent the range of F you found above requires $\qquad$ (how many) bits.
c. Design the circuit to generate the appropriate number of outputs for F using a single 4bit adder and a minimal number of full and half adders along with simple AND, OR, NOT gates. [Hint: W-X-Y-Z = W - (X+Y+Z)]

Feel free to add/use a minimal number of additional full and half adders such as these

6. FPGAs/Memories Design (10 pts.): Consider the circuit shown below. Show how to implement the design using the two 3-input, 2-output CLBs below by determining the contents of the $8 \times 2$ memory and the mux selects. If necessary, place a dash ('-') in any memory cell (bit place) that is a don't care.


Circuit to be implemented using the CLB's below

7. Sequential Logic (12 pts.): Complete the waveform diagram below for D0, Q0, D1, Q1 and F. Assume the D flip-flops shown below are positive-edge triggered. Q0 starts at 1 and Q1 starts at 0 . (You can determine the starting value of D0, D1, and F from the given information.)

Hint: You can find the waveforms for D0 and Q0 using only the left half of the circuit and then use those results to find D1, Q1, and F.

8. Interrupts and Arduino Coding (8 pts.) Your Arduino needs to output the two periodic signals shown below (which only show a few cycles of the desired pattern which continue indefinitely) on Port D, bit 2 (PD2) and Port D, bit 3 (PD3). The signal on PD2 has a period of 30 ms and duty cycle of $33.3 \%$ (high for 10 ms , low for 20 ms ). The signal on 3 has a period of 40 ms and duty cycle of $50 \%$ (high for 20 ms , low for 20 ms ).


You must use the 16 -bit TIMER1 to produce both signals. You may not use any delay functions to produce the output. Determine the prescaler and counter modulus value (max count) to store in the OCR1A register, and write the ISR (TIMER1_COMPA_vect) that will generate the desired signals. If multiple pairs of prescalar and modulus values will work, use ones that give the more accurate timing. Note: The Arduino system clock is 16 MHz . (note: 1 millisecond $(\mathrm{ms})=10^{-3}$ seconds, 1 microsecond $(\mu \mathrm{s})=10^{-6}$ seconds)

## Complete your answers in the linked sp21-fi-isr.c file and then upload the completed file to Gradescope. The contents are reproduced below.

// Inidicate what prescalar you choose by deleting the options you don't
// want then write your chosen OCR value below.
// ---------- FILL IN THE 2 LINES BELOW ----------------
// Prescalar: 1 / 8 / 64 / 256 / 1024
// OCR1A: $\qquad$
// Assume the outputs have been initialized and set to output a '1', the
// TIMER1 is initialized correctly with the values you chose above, and
// that interrupts have been enabled so that the ISR below is called each time
// TIMER1 reaches your OCR1A value.
// --------- COMPLETE THE CODE BELOW
// declare any needed global variables here

ISR(TIMER1_COMPA_vect)
\{ // show ISR code here..NO delay functions are allowed (losing all credit)
\}

Intentionally blank for scratch work. You may detach it but please turn it in with your exam:
Name: $\qquad$ Section time: $\qquad$


